

Mathematical Statistics, Centre for Mathematical Sciences, Lund University
 Exam in Stationary stochastic processes (FMSF10/MASC04)

Date: 2017-10-28

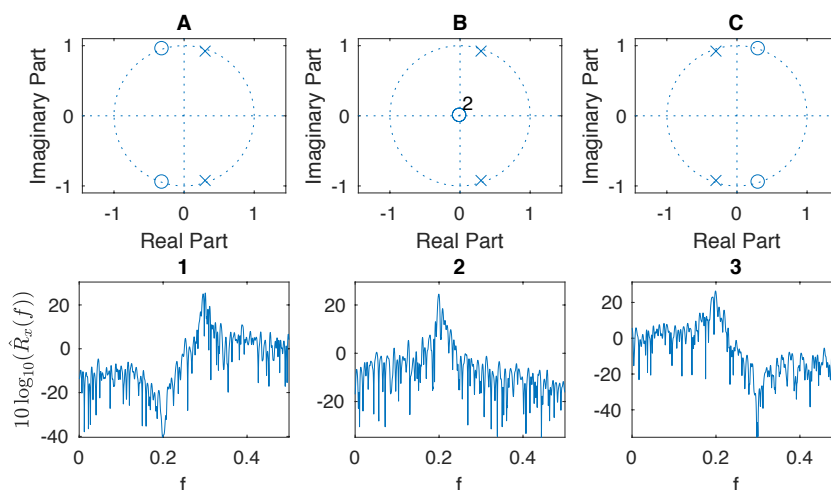
Time: 8.00 – 13.00

Help: Calculator, table of formulas in stationary stochastic processes, small table of formulas in mathematics.

Solutions, correct and well motivated, of exercise 1-3 give 10 credits, and of exercise 4-6 give 20 credits. The maximal number of credits are 90. The limit for passing the course is 40 credits. Each exercise should have a solution starting on a new sheet of paper.

- 1) a) The figure shows the pole-zero plots of three different discrete time models of stationary processes and modified periodogram estimates of one realization from each model. A Hanning window is used as data window and the spectral estimates are presented in dB-scale. Combine the pole-zero plot with the corresponding spectral estimate. Motivate your answer. Also state which type of model (AR, MA or ARMA) in each case and the corresponding order.

(6p)



- b) We have access to 1024 samples of data, where the true spectral density function is $R_X(f)$. The Welch method, with window length 256 in each periodogram and 50% overlap between windows, is applied. Approximately how large is the variance for $0 < |f| < 0.5$? Motivate your answer.

(4p)

- 2) An MA(q)-process $X_t, t = 0, \pm 1, \pm 2, \dots$, is defined as

$$X_t = e_t + b_1 e_{t-1} + b_2 e_{t-2} + \dots + b_q e_{t-q},$$

where e_t is white Gaussian noise with $V[e_t] = 1$. The covariance function is $r_X(0) = 2$, $r_X(\pm 3) = 1$ and zero for all other values of τ . Determine the order of the process q , the parameters $b_1 \dots b_q$ and the spectral density.

(10p)

3) A zero-mean, weakly stationary, Gaussian process $X(t)$, $t \in \mathbb{R}$, has the spectral density

$$R_X(f) = \pi e^{-2\pi|f|}.$$

State, with a short motivation, for each of the following statements if it is right or wrong. Each correct answer with correct motivation gives 2 credits.

a) The covariance function is

$$r_X(\tau) = \frac{1}{1 + \tau^2}.$$

b) The process is differentiable in quadratic mean.

c) The variance

$$V\left[\frac{X(0) + X(t)}{2}\right]$$

approaches zero when $t \rightarrow \infty$.

d) After filtering through a linear filter with frequency function

$$H(f) = 1 + if$$

the spectral density of the process is constant for all frequencies.

e) A new process

$$Y(t) = 3X(t) - 2X'(t)$$

is created. The process $Y(t)$ is a Gaussian process.

(10p)

4) For an AR(2)-process X_t , $t = 0, \pm 1, \pm 2, \dots$, the following covariance values are given,

$$r_X(\tau) = \begin{cases} 12 & \tau = 0, \\ 8 & |\tau| = 1, \\ 2 & |\tau| = 2, \\ -2 & |\tau| = 3. \end{cases}$$

a) Determine the spectral density of the AR(2)-process. For full number of credits, a real-valued expression should be presented.

(14p)

b) Compute the frequency function of a Wiener filter which reconstructs the AR(2)-process X_t from the measurement data $Y_t = X_t + N_t$, where N_t , $t = 0, \pm 1, \pm 2, \dots$, is a Gaussian white noise sequence with $E[N_t] = 0$ and $V[N_t] = 4$. Note that the expression should be simplified as far as possible and written in real-valued form.

(6p)

- 5) We define the weakly stationary Gaussian process $Y(t) = m + X(t)$, $t \in \mathbb{R}$, where m is an unknown constant expected value. The process $X(t)$ is assumed to have $E[X(t)] = 0$ and spectral density

$$R_X(f) = \begin{cases} 1 & \text{for } |f - 2.1| \leq 0.1, \\ 1 & \text{for } |f + 2.1| \leq 0.1 \\ 0 & \text{otherwise.} \end{cases}$$

An estimate of m should be found as

$$\hat{m}_n = \frac{Y(d) + Y(2d) + \dots + Y(nd)}{n},$$

by sampling the process $Y(t)$ with sample distance d . There are two possible choices of sample distances, $d = 1/4$ and $d = 1/2$.

- a) Calculate the covariance function $r_Y(\tau)$.

(4p)

- b) Determine the spectral density of the sampled process $Z_t = Y(t)$, $t = 0, \pm d, \pm 2d, \dots$ for the two suggested sample distances, $d = 1/4$ and $d = 1/2$.

(10p)

- c) Determine $nV[\hat{m}_n]$, when $n \rightarrow \infty$ for $d = 1/4$ and $d = 1/2$. Which of the suggested sample distances would you prefer?

(6p)

- 6) A zero-mean weakly stationary process $X(t)$, $t \in \mathbb{R}$, has the covariance function

$$r_X(\tau) = e^{-\tau^2/2}.$$

The measurements of $X(t)$ are disturbed by zero-mean, additive measurement noise $e(t)$, giving $Y(t) = X(t) + e(t)$. The disturbance is assumed to have the covariance function

$$r_e(\tau) = \begin{cases} \sigma^2 & \text{for } |\tau| \leq h/2, \\ 0 & \text{for } |\tau| > h/2. \end{cases}$$

The derivative of $X(t)$ should be approximated using

$$Z(t) = \frac{aY(t) - bY(t-h)}{h}.$$

- a) Calculate an expression for the variance $V[Z(t)]$.

(5p)

- b) Find an expression for the cross-covariance $r_{X',Z}(\tau) = C[X'(t), Z(t+\tau)]$ where $X'(t)$ is the true derivative of $X(t)$.

(5p)

- c) Minimize the mean squared error $E[(X'(t) - Z(t))^2]$ for $\sigma^2 = 1$, $h = 0.5$ and find the corresponding optimal values of a and b .

(10p)